

#### FEATURES

AC performance Unity-gain bandwidth: 40 MHz Fast settling time: 110 ns to 0.01% Slew rate: 300 V/μs Full power bandwidth: 4.7 MHz for 20 V p-p into a 500 Ω load DC performance Input offset voltage: 1 mV maximum Input voltage noise: 15 nV/√Hz typical Open-loop gain: 45 V/mV into a 1 kΩ load Output current: 50 mA minimum Supply current: 12 mA maximum

#### **APPLICATIONS**

High speed signal conditioning Video and pulse amplifiers Data acquisition systems Line drivers Active filters Available in 14-pin plastic PDIP, 14-pin hermetic CERDIP, and 20-pin LCC packages Chips and MIL-STD-883B parts available

## Wideband, Unity-Gain Stable, Fast Settling Op Amp

## **AD841**

#### **CONNECTION DIAGRAMS**



Figure 1. PDIP (N-14) Package and CERDIP (Q-14) Package



#### **GENERAL DESCRIPTION**

The AD841 is a member of the Analog Devices, Inc., family of wide bandwidth operational amplifiers. This high speed/high precision family includes the AD842, which is stable at a gain of two or greater and has 100 mA minimum output current drive. These devices are fabricated using Analog Devices' junction isolated complementary bipolar (CB) process. This process permits a combination of dc precision and wideband ac performance previously unobtainable in a monolithic op amp. In addition to its 40 MHz unity-gain bandwidth product, the AD841 offers extremely fast settling characteristics, typically settling to within 0.01% of final value in 110 ns for a 10 V step.

Unlike many high frequency amplifiers, the AD841 requires no external compensation. It remains stable over its full operating temperature range. It also offers a low quiescent current of 12 mA maximum, a minimum output current drive capability of 50 mA, a low input voltage noise of 15 nV/ $\sqrt{Hz}$ , and low input offset voltage of 1 mV maximum.

The 300 V/µs slew rate of the AD841, along with its 40 MHz gain bandwidth, ensures excellent performance in video and pulse amplifier applications. This amplifier is well suited for

use in high frequency signal conditioning circuits and wide bandwidth active filters. The extremely rapid settling time of the AD841 makes it the preferred choice for data acquisition applications that require 12-bit accuracy. The AD841 is also appropriate for other applications such as high speed DAC and ADC buffer amplifiers and other wide bandwidth circuitry.

#### **PRODUCT HIGHLIGHTS**

- 1. The high slew rate and fast settling time of the AD841 make it ideal for DAC and ADC buffers, and all types of video instrumentation circuitry.
- 2. The AD841 is a precision amplifier. It offers accuracy to 0.01% or better and wide bandwidth performance previously available only in hybrids.
- 3. The AD841's thermally balanced layout and the speed of the CB process allow the AD841 to settle to 0.01% in 110 ns without the long tails that occur with other fast op amps.
- 4. Laser wafer trimming reduces the input offset voltage to 1 mV maximum on the K grade, thus eliminating the need for external offset nulling in many applications. Offset null pins are provided for additional versatility.

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## **REVISION HISTORY**

#### 2/13-Rev. B to Rev. C

Removed TO-8 Package	Universal
Changed Input Voltage Noise 13 nV/ $\sqrt{Hz}$ to 15 nV/ $\sqrt{I}$	Hz and
Changes to General Description Section	1
Changes to Endnote 1, Table 1	4
Added Operating Temperature Range, Table 2	5
Deleted Using a Heat Sink Section	11
Updated Outline Dimensions	13
Added Ordering Guide	14

11/88—Rev. A to Rev. B

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## **SPECIFICATIONS**

 $T_A$  = 25°C and ±15 V dc, unless otherwise noted. All minimum and maximum specifications are guaranteed.

#### Table 1.

	Test Conditions/		AD841J			AD841K	(		AD8415	1	
Parameter	Comments	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Unit
INPUT OFFSET VOLTAGE <sup>2</sup>			0.8	2.0		0.5	1.0		0.5	2.0	mV
	T <sub>MIN</sub> – T <sub>MAX</sub>			5.0			3.3		5.5		mV
Offset Drift			35			35			35		μV/°C
INPUT BIAS CURRENT			3.5	8		3.5	5		3.5	8	μA
	T <sub>MIN</sub> – T <sub>MAX</sub>			10			6			12	μA
Input Offset Current			0.1	0.4		0.1	0.2		0.1	0.4	μA
	T <sub>MIN</sub> – T <sub>MAX</sub>			0.5			0.3			0.6	μA
INPUT CHARACTERISTICS	Differential mode										
Input Resistance			200			200			200		kΩ
Input Capacitance			2			2			2		рF
INPUT VOLTAGE RANGE											
Common Mode		±10	12		±10	12		±10	12		v
Common-Mode Rejection	$V_{CM} = \pm 10 V$	86	100		103	109		86	110		dB
,	T <sub>MIN</sub> – T <sub>MAX</sub>	80			100			80			dB
INPUT VOLTAGE NOISE	f = 1 kHz	-	15			15			15		nV/√Hz
Wideband Noise	10 Hz to 10 MHz		47			47			47		μV rms
OPEN-LOOP GAIN	$V_{OUT} = \pm 10 V$										
	$R_{LOAD} \ge 500 \Omega$	25	45		25	45		25	45		V/mV
	T <sub>MIN</sub> – T <sub>MAX</sub>	12			20			12			V/mV
OUTPUT CHARACTERISTICS											.,
Voltage	$R_{LOAD} \ge 500 \Omega$										
Voltage	$T_{MIN} - T_{MAX}$	±10			±10			±10			v
Current	$V_{OUT} = \pm 10 V$	50			50			50			mA
OUTPUT RESISTANCE	Open loop		5			5			5		Ω
FREQUENCY RESPONSE	openieop		5			5			5		
Unity Gain Bandwidth	V <sub>OUT</sub> = 90 mV p-p		40			40			40		MHz
Full Power Bandwidth <sup>3</sup>	$V_{OUT} = 20 V p - p$		10			10			10		141112
	$R_{LOAD} \ge 500 \Omega$	3.1	4.7		3.1	4.7		3.1	4.7		MHz
Rise Time⁴	$A_V = -1$	5.1	10		5.1	10		5.1	10		ns
Overshoot <sup>₄</sup>	$A_V = -1$		10			10			10		%
Slew Rate <sup>4</sup>	$A_V = -1$ $A_V = -1$	200	300		200	300		200	300		ν/μs
Settling Time 10 V Step	$A_V = -1$ $A_V = -1$	200	300		200	500		200	300		v/μs
Setting time to v Step	to 0.1%		90			00			90		ns
	to 0.01%		90 110			110			90 110		ns
OVERDRIVE RECOVERY	–Overdrive		200			200			200		-
OVERDRIVE RECOVERT	+Overdrive		200 700			700			200 700		ns
DIFFERENTIAL GAIN	f = 4.4 MHz		0.03			0.03			0.03		ns %
Differential Phase	f = 4.4  MHz		0.03			0.03			0.03		
POWER SUPPLY			0.022		1	0.022		1	0.022		Degree
			.15			.15			. 15		v
Rated Performance			±15	110		±15	10		±15	110	v
Operating Range		±5	11	±18	±5	11	±18	±5	11	±18	
Quiescent Current			11	12		11	12		11	12 16	mA
	$T_{MIN} - T_{MAX}$	0.5	100	14	00	100	14	06	100	16	mA
Power Supply Rejection Ratio	$V_s = \pm 5 V \text{ to } \pm 18 V$	86	100		90	100		86	100		dB
	$T_{MIN} - T_{MAX}$	80			86			80			dB

## AD841

	Test Conditions/		AD841J			AD841K			AD841S <sup>1</sup>		
Parameter	Comments	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Unit
TEMPERATURE RANGE											
Rated Performance <sup>5</sup>		0		70	0		70	-55		+125	°C

<sup>1</sup> Standard military drawing available: 5962-89641012A – (SE/883B). <sup>2</sup> Input offset voltage specifications are guaranteed after 5 minutes at T<sub>A</sub> = 25°C. <sup>3</sup> Full power bandwidth = slew rate/2 π V<sub>PEAK</sub>. <sup>4</sup> Refer to Figure 22 to Figure 24. <sup>5</sup> S grade T<sub>MIN</sub> – T<sub>MAX</sub> specifications are tested with automatic test equipment at T<sub>A</sub> = -55°C and T<sub>A</sub> = +125°C.

## **ABSOLUTE MAXIMUM RATINGS**

#### Table 2.

Table 2.				
Parameter	Rating			
Supply Voltage (Vs)	±18 V			
Internal Power Dissipation <sup>1</sup>				
PDIP (N-14)	1.5 W			
CERDIP (Q-14)	1.3 W			
Input Voltage	±Vs			
Differential Input Voltage	±6 V			
Storage Temperature Range				
Q-14	–65°C to +150°C			
N-14	–65°C to +125°C			
Operating Temperature Range				
AD841J/AD841K	0°C to 70°C			
AD841S	−55°C to +125°C			
Junction Temperature	+175°C			
Lead Temperature Range (Soldering 60 sec)	+300°C			

 $^1$  Maximum internal power dissipation is specified so that  $T_{\rm J}$  does not exceed 175°C at an ambient temperature of 25°C.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### THERMAL CHARACTERISTICS

#### Table 3.

Package Type	οις	θ <sub>JA</sub>	θsa	Unit
14-Lead CERDIP	35	110	38	°C/W
14-Lead PDIP	30	100		°C/W
20-Lead LCC	35	150		°C/W

#### **ESD CAUTION**



**ESD** (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.



Dimensions shown in inches and (millimeters)

## **TYPICAL PERFORMANCE CHARACTERISTICS**

 $T_{\text{A}}$  = 25°C and Vs = ±15 V, unless otherwise noted.





## AD841



## AD841



#### R<sub>F</sub> 1kΩ +Vs 0.1µF HP3314A FUNCTION GENERATOR OR EQUIVALENT 2.2µF R<sub>IN</sub> 1kΩ \$49.9Ω AD841 ον<sub>ουτ</sub> 10 ≹499Ω √ 0.1µF R<sub>B</sub> 499Ω 211 11340-022 -Vs ¢

Figure 22. Inverting Amplifier Configuration (PDIP Pinout)



Figure 23. Inverter Large Signal Pulse Response

11340-023

11340-024



Figure 24. Inverter Small Signal Pulse Response



Figure 25. Unity-Gain Buffer Amplifier Configuration (PDIP Pinout)



Figure 26. Buffer Large Signal Pulse Response



Figure 27. Buffer Small Signal Pulse Response

## AD841

11340-026

11340-027

# THEORY OF OPERATION OFFSET NULLING

The input offset voltage of the AD841 is very low for a high speed op amp, but if additional nulling is required, the circuit shown in Figure 28 can be used.



Figure 28. Offset Nulling (PDIP Pinout)

#### INPUT CONSIDERATIONS

An input resistor ( $R_{IN}$  in Figure 25) is recommended in circuits where the input to the AD841 is subjected to transient or continuous overload voltages exceeding the ±6 V maximum differential limit. This resistor provides protection for the input transistors by limiting the maximum current that can be forced into the input.

For high performance circuits it is recommended that a resistor ( $R_B$  in Figure 22 and Figure 25) be used to reduce bias current errors by matching the impedance at each input. The output voltage error caused by the offset current is more than an order of magnitude less than the error present if the bias current error is not removed.

## AD841 SETTLING TIME

Figure 29 and Figure 31 show the settling performance of the AD841 in the test circuit shown in Figure 30.

Settling time is defined as the interval of time from the application of an ideal step function input until the closed-loop amplifier output has entered and remains within a specified error band.

This definition encompasses the major components, which comprise settling time. They include

- Propagation delay through the amplifier
- Slewing time to approach the final output value
- The time of recovery from the overload associated with slewing
- Linear settling to within the specified error band

Expressed in these terms, the measurement of settling time is obviously a challenge and needs to be done accurately to assure the user that the amplifier is worth consideration for the application.



Figure 29. AD841 0.01% Settling Time



Figure 30. Settling Time Test Circuit

Measurement of the 0.01% settling in 110 ns was accomplished by amplifying the error signal from a false summing junction with a very high speed proprietary hybrid error amplifier specially designed to enable testing of small settling errors. The device under test was driving a 500  $\Omega$  load. The input to the error amp is clamped to avoid possible problems associated with the overdrive recovery of the oscilloscope input amplifier. The error amp gains the error from the false summing junction by 10, and it contains a gain vernier to fine trim the gain.

Figure 31 shows the long-term stability of the settling characteristics of the AD841 output after a 10 V step. There is no evidence of settling tails after the initial transient recovery time. The use of a junction isolated process, together with careful layout, avoids these problems by minimizing the effects of transistor isolation capacitance discharge and thermally induced shifts in circuit operating points. These problems do not occur even under high output current conditions.



Figure 31. AD841 Settling Demonstrating No Settling Tails

#### **GROUNDING AND BYPASSING**

In designing practical circuits with the AD841, the user must remember that whenever high frequencies are involved, some special precautions are in order. Circuits must be built with short interconnect leads. Large ground planes should be used whenever possible to provide a low resistance, low inductance circuit path, as well as minimizing the effects of high frequency coupling. Avoid sockets because the increased interlead capacitance can degrade bandwidth.

Feedback resistors should be of low enough value to assure that the time constant formed with the circuit capacitances will not limit the amplifier performance. Resistor values of less than 5 k $\Omega$  are recommended. If a larger resistor must be used, a small (<10 pF) feedback capacitor in parallel with the feedback resistor, R<sub>F</sub>, may be used to compensate for these stray capacitances and optimize the dynamic performance of the amplifier in the particular application.

Bypass power supply leads to ground as close as possible to the amplifier pins. A 2.2  $\mu F$  capacitor in parallel with a 0.1  $\mu F$  ceramic disk capacitor is recommended.

#### **CAPACITIVE LOAD DRIVING ABILITY**

Like all wideband amplifiers, the AD841 is sensitive to capacitive loading. The AD841 is designed to drive capacitive loads of up to 20 pF without degradation of its rated performance. Capacitive loads of greater than 20 pF will decrease the dynamic performance of the part although instability should not occur unless the load exceeds 100 pF (for a unity-gain follower). A resistor in series with the output can be used to decouple larger capacitive loads.

Figure 32 shows a typical configuration for driving a large capacitive load. The 51  $\Omega$  output resistor effectively isolates the high frequency feedback from the load and stabilizes the circuit. Low frequency feedback is returned to the amplifier summing junction via the low-pass filter formed by the 51  $\Omega$  resistor and the load capacitance,  $C_{L}$ .



Figure 32. Circuit for Driving a Large Capacitive Load

#### **TERMINATED LINE DRIVER**

The AD841 functions very well as a high speed line driver of either terminated or unterminated cables. Figure 33 shows the AD841 driving a doubly terminated cable in a follower configuration. The AD841 maintains a typical slew rate of 300 V/ $\mu$ s, which means it can drive a ±10 V, 4.7 MHz signal or a ±3 V, 15.9 MHz signal.

The termination resistor,  $R_T$ , (when equal to the characteristic impedance of the cable) minimizes reflections from the far end of the cable. A back-termination resistor,  $R_{BT}$ , (also equal to the characteristic impedance of the cable) may be placed between the AD841 output and the cable to damp any stray signals caused by a mismatch between  $R_T$  and the cable's characteristic impedance. This results in a cleaner signal, but because half the output voltage is dropped across  $R_{BT}$ , the op amp must supply double the output signal required if there is no back termination. Therefore, the full power bandwidth is cut in half.

If termination is not used, cables appear as capacitive loads. If this capacitive load is large, it should be decoupled from the AD841 by a resistor in series with the output (see Figure 32).



#### **OVERDRIVE RECOVERY**

Figure 34 shows the overdrive recovery capability of the AD841. Typical recovery time is 200 ns from negative overdrive and 700 ns from positive overdrive.







Figure 35. Overdrive Recovery Test Circuit

## **OUTLINE DIMENSIONS**





#### **ORDERING GUIDE**

Model <sup>1</sup>	Iodel <sup>1</sup> Temperature Range Package Description		Package Option		
AD841JNZ	0°C to +70°C	14-Lead Plastic Dual In-Line Package [PDIP]	N-14		
AD841KNZ	0°C to +70°C	14-Lead Plastic Dual In-Line Package [PDIP]	N-14		
AD841JCHIPS		Die			
AD841SCHIPS		Die			
AD841SE	–55°C to +125°C	20-Terminal Ceramic Leadless Chip Carrier [LCC]	E-20-1		
AD841SE/883B	−55°C to +125°C	20-Terminal Ceramic Leadless Chip Carrier [LCC]	E-20-1		
AD841SQ	–55°C to +125°C	14-Lead Ceramic Dual In-Line Package [CERDIP]	Q-14		
AD841SQ/883B	−55°C to +125°C	14-Lead Ceramic Dual In-Line Package [CERDIP]	Q-14		

 $^{1}$  Z = RoHS Compliant Part.

## NOTES

## AD841

## NOTES

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